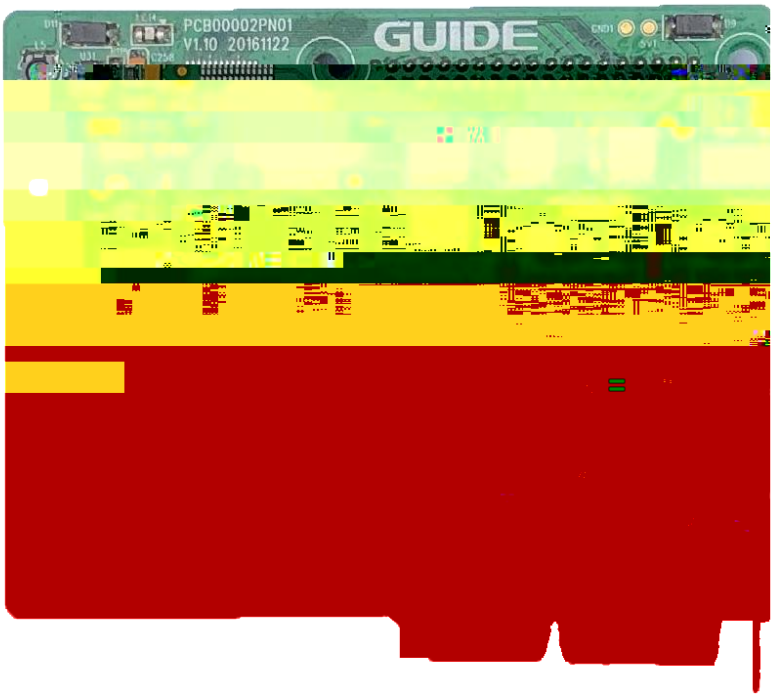
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GDHF-PN01



Wuhan Guide Technology Co.,Ltd

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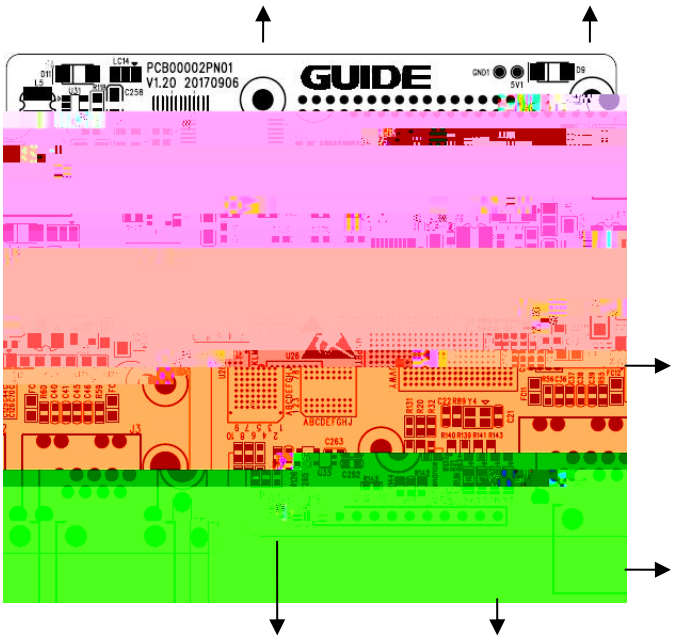
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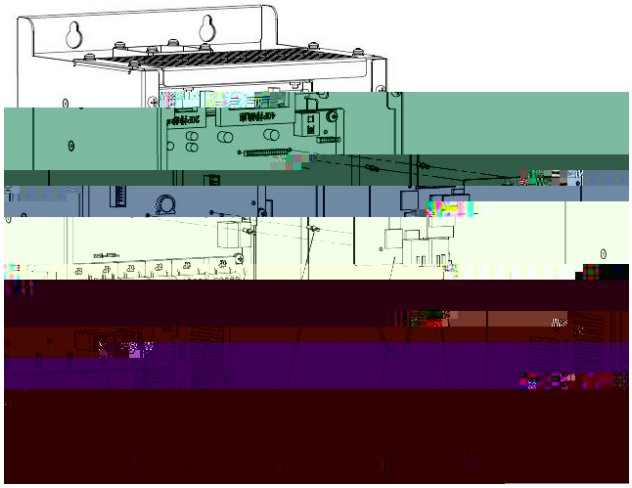
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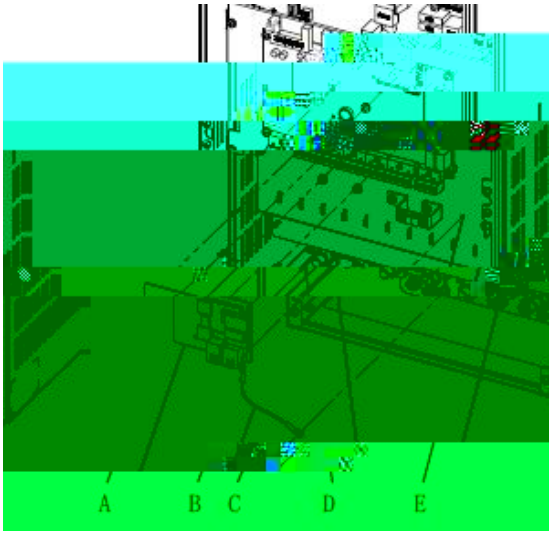
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W0	PA_CTRL ő L	bit	w	
		0	PA_ENABLE	‘0’ Ь ą ő ḱ ‘1’ ą ő ḱ
		1	WRITE	‘0’ ‘1’ Ώ
		2	SAVE_to_FLASH	‘0’ Ь ƀ ‘1’ Ḡ ⌡ FLASH
		3 ~ 15	Reserved	
W1	Address	byte	[15..08]	[07..00]
		Data	ő	ő ↷
W2	0	0		
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CW0.11	Torque_Limit_Ctrl	└ ẏ ‘0’ ṗ ă ‘1’ PROFINET
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CW0.13 β		
CW0.14	TORQUE_ZERO	ẇ ‘0’ Ь ą ‘1’ ą ẇ
CW0.15	FREE_RUNNING_STOP	Å ‘0’ Ь ƀ ‘1’ Å

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SW0.0	READY	ΐ ‰ Ḥ ‘ 0 ’ ΐ ‰ ‘ 1 ’ ΐ ‰
SW0.1	RUN	ΐ ‘ 0 ’ ΐ Å ‘ 1 ’ ΐ ض
SW0.2	FAULT	‘ 0 ’ ΐ ‘ 1 ’ ΐ
SW0.3	MOTOR BRAKE	Ḥ ‘ 0 ’ Ḥ ‘ 1 ’ Ḥ
SW0.4	WARNING	ɒ Ḥ ‘ 0 ’ ΐ ɒ ‘ 1 ’ ɒ
SW0.5	DIRECTION	h ‘ 0 ’ h ‘ 1 ’ ΐ h
SW0.6	M_STEP0	1 ‘ 0 ’ 1 Ḥ ‘ 1 ’ 1 Ḥ
SW0.7	M_STEP1	2 ‘ 0 ’ 2 Ḥ ‘ 1 ’ 2 Ḥ

SW0.8	M_STEP2	3 ‘0’ 3 Ḥ ‘1’ 3 Ḥ
SW0.9	M_STEP3	4 ‘0’ 4 Ḥ ‘1’ 4 Ḥ
SW0.10	Reserved	
SW0.11	Reserved	
SW0.12	REMOTE/LOCAL	/ض ‘0’ ‘1’ ض
SW0.13	Reserved	
SW0.14 γ β	MOTION SEL	‘00’ 1 ‘01’ 2 ‘10’ 3 ‘11’ 4
SW0.15 β		

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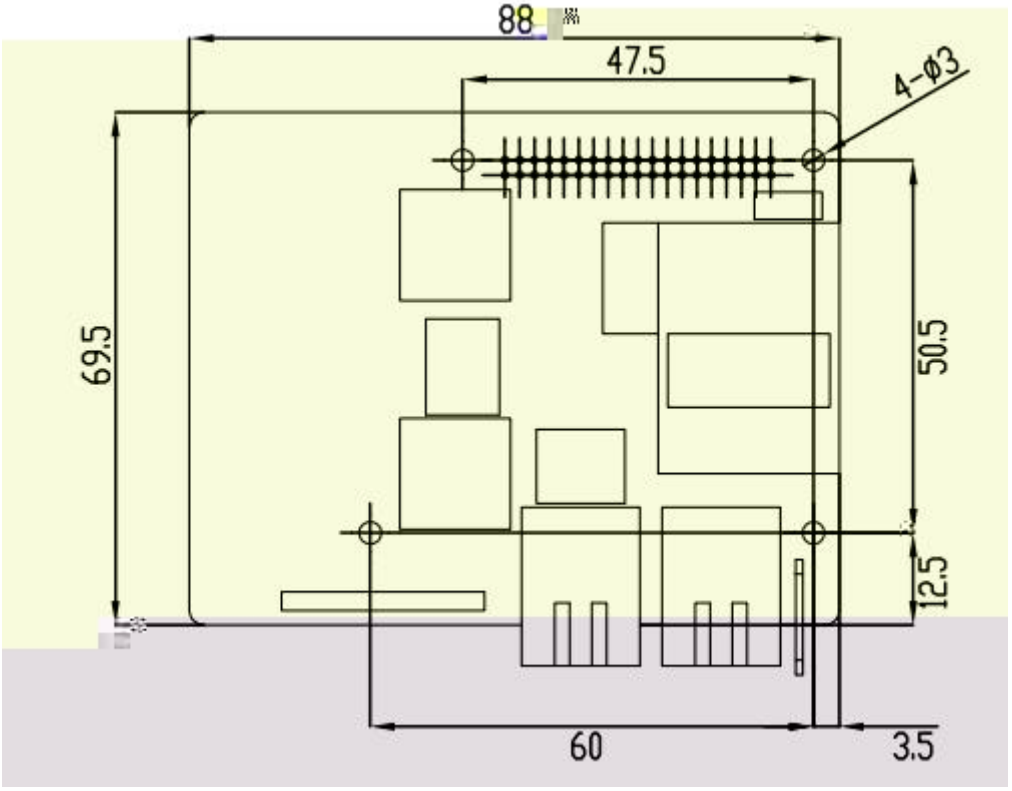
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